

# The Horse Raced Past: Gardenpath Processing in Dynamical Systems

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# the



# horse



# raced



# past



# the



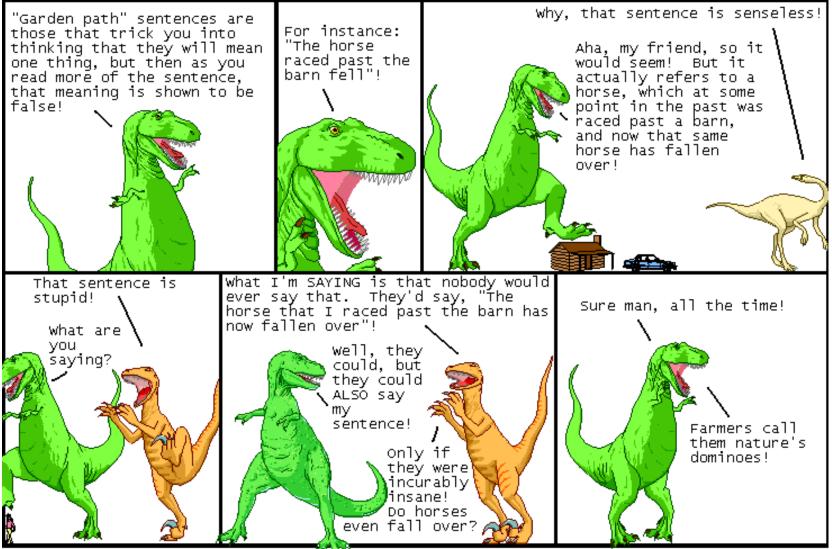
# barn



# fell.



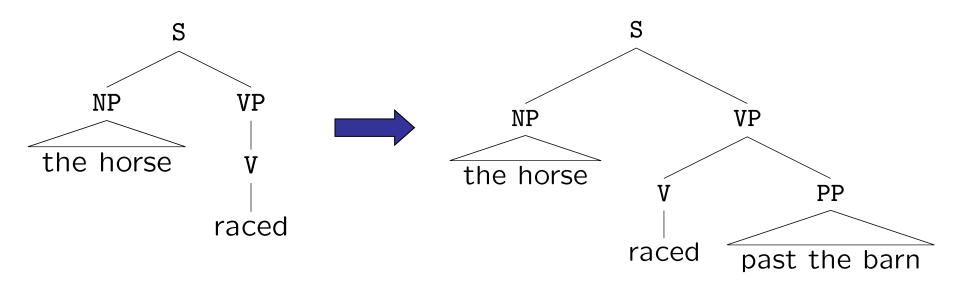




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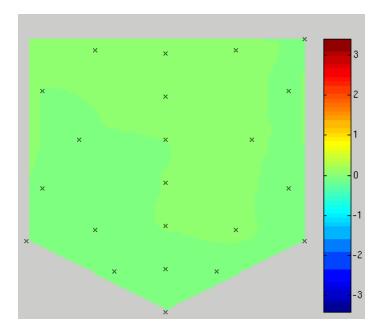


late closure



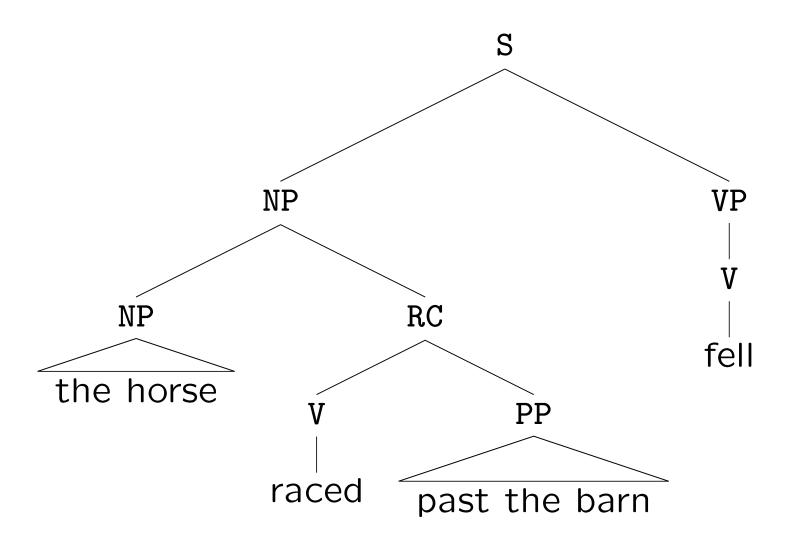


- Self-paced reading: slowing down
- Eye-tracking: regressions, longer fixations
- Event-related brain potentials: P600



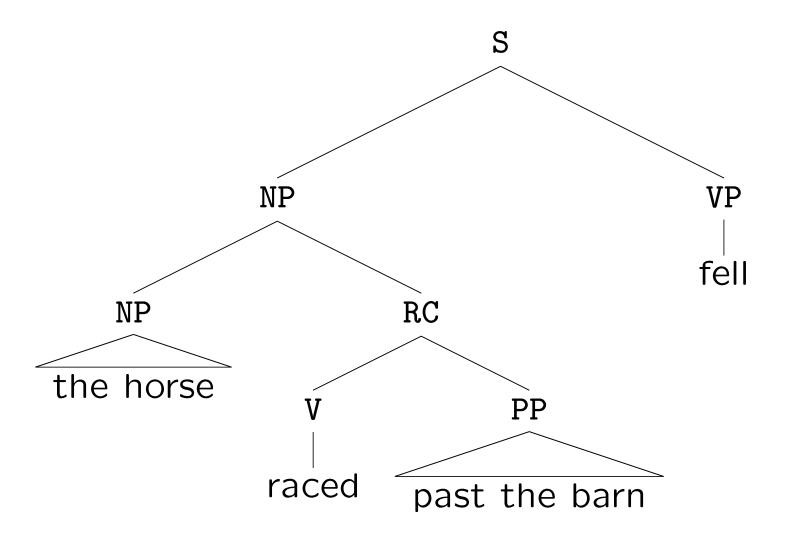






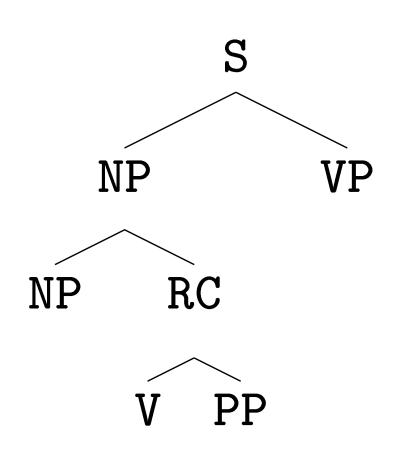
## Simplified





#### Context-Free Grammars





$$S o NP VP$$
.

 $NP o NP RC$ .

 $RC o V PP$ 

$$extstyle S o extstyle extstyle$$





1

stack				
input	the horse	raced	past the barn	fell

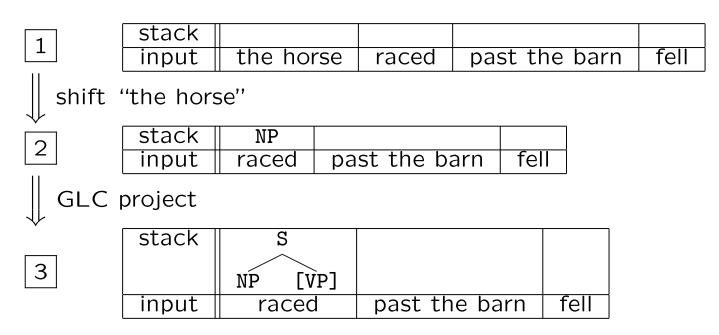




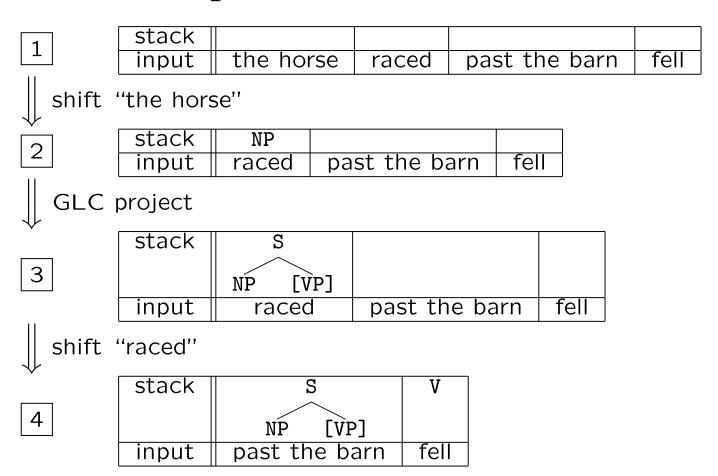
1	stack input	the hor	se	raced	l pa:	st the	barn	fell
	the hors	se''			·			
	stack	NP						
	input	raced	pas	st the	barn	fell		



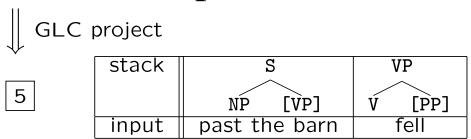




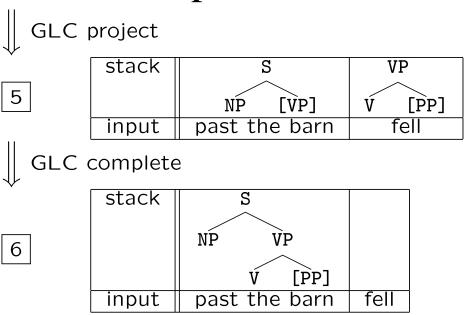






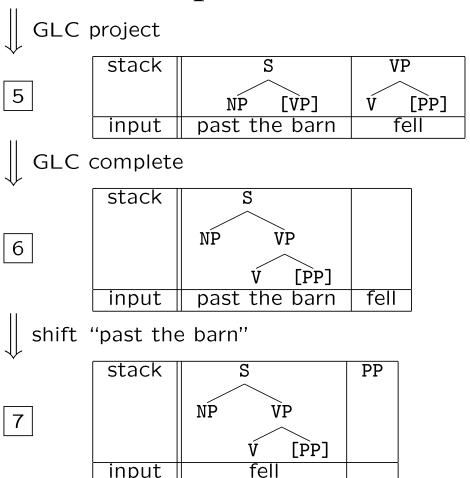




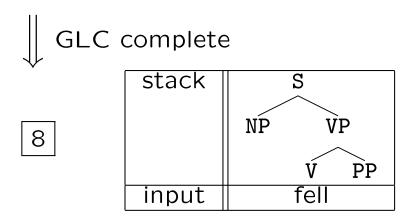






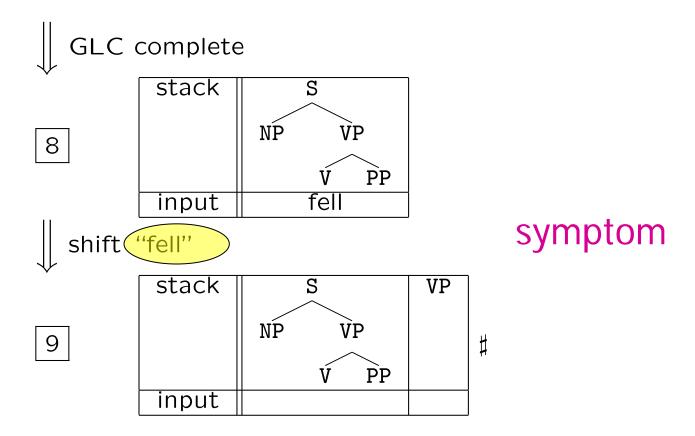












### Diagnosis



The horse raced past the barn fell.

The horse raced past. The barn fell.

?

#### Lexicon:

raced = (1) finite verb, past tense

raced = (2) non-finite verb, participle past perfect





9

	stack	S	VP
		NP VP	
		111 11	
		V PP	
Ì	input		

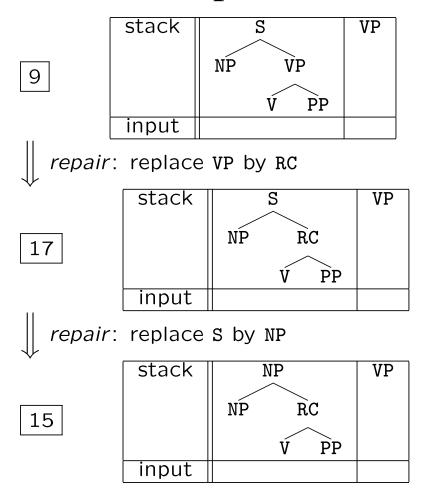




	stack	S	VP		
9		NP VP			
		V PP			
	input				
repair: replace VP by RC					
	stack	S	VP		
17		NP RC V PP			
	input				







Fodor & Inoue (1994) Lewis (1998)



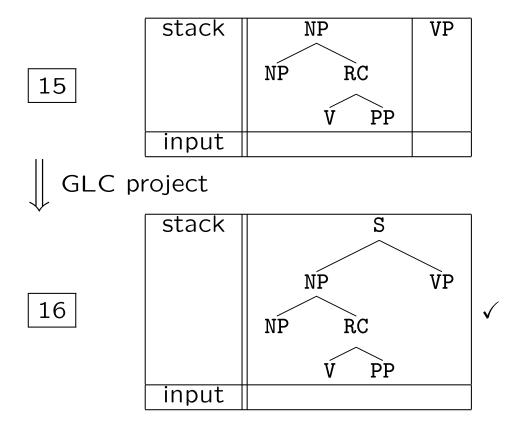


15

stack	NP			VP
	NP RC			
		V	PP	
input				





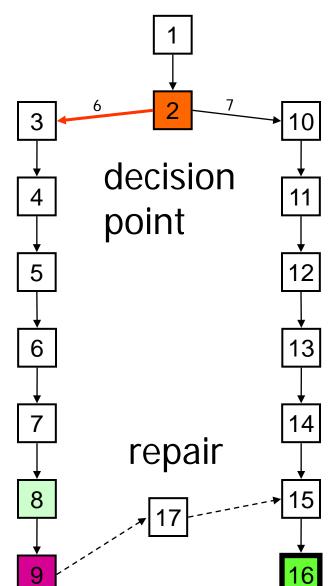






weighted directed graph

default path



A\* search: arrive rapidly!

Hale (2011)







embedding into Euclidian space

### Weights



in Euclidian geometry, arc weights could become

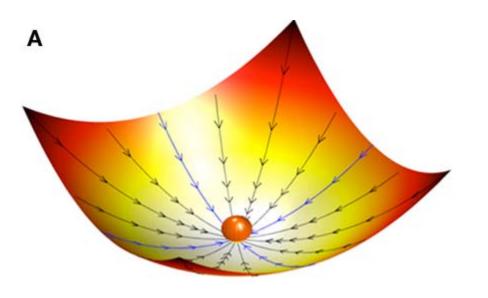
- 1. distances
- 2. transition times

only for constant velocity, 1. and 2. are equivalent

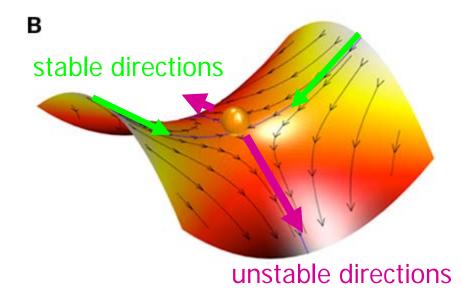




identify parser states with equilibrium points in geometric space



fixed point attractor



saddle node



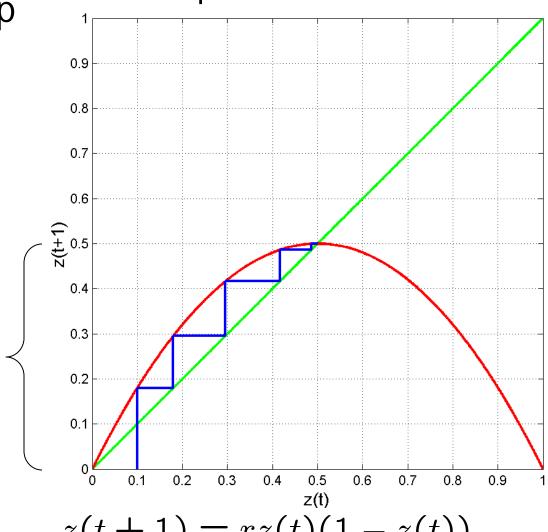
### Example

logistic map

control

parameter *r* 

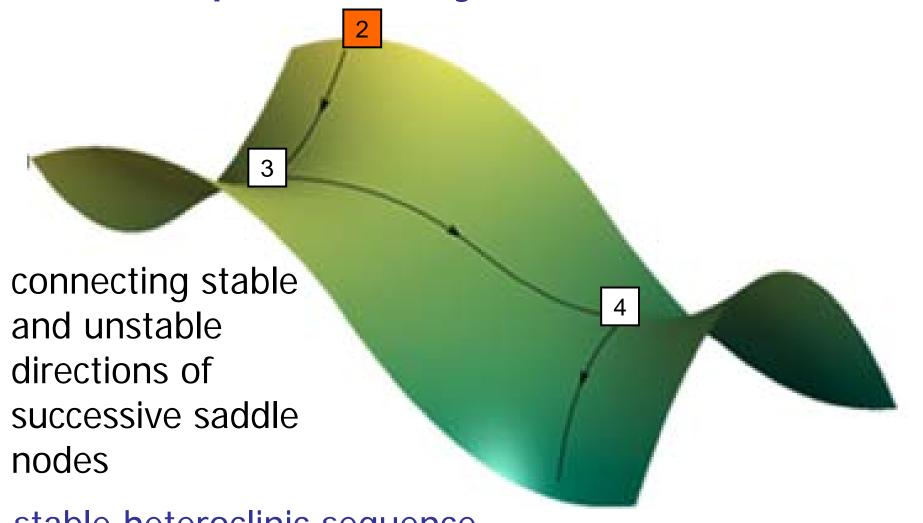
fixed point attractor



$$z(t+1) = rz(t)(1-z(t))$$





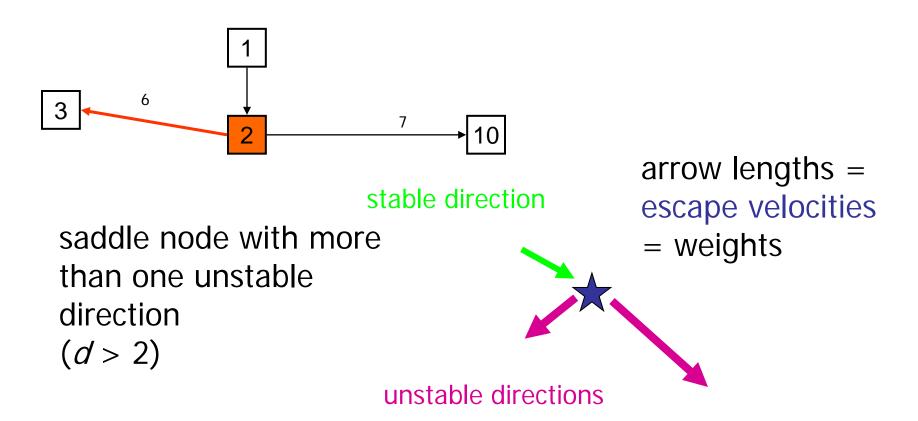


stable heteroclinic sequence (SHS)

Afraimovich et al. (2004) Rabinovich et al. (2008)

### Sequential Decision Problems

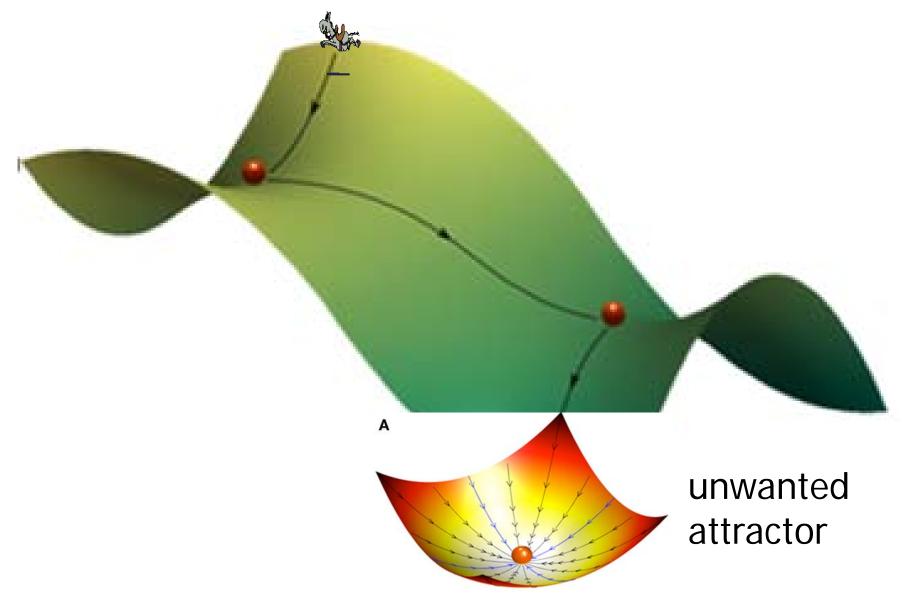




A\* search = high risk decision for large velocities

## Gardenpath States



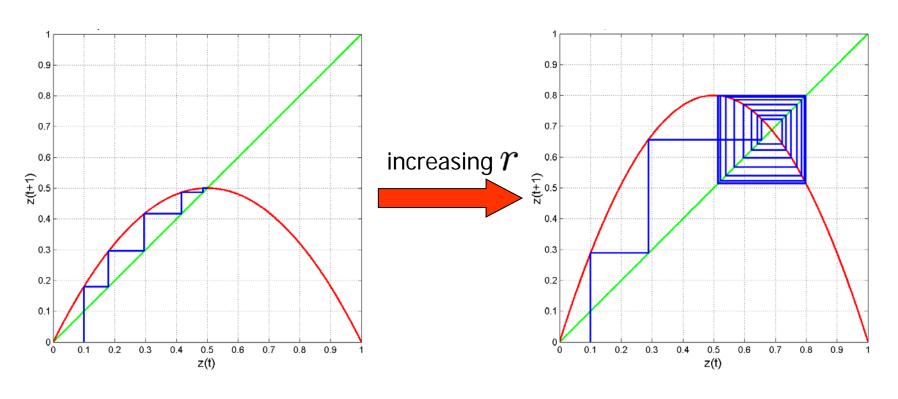


#### **Bifurcations**



#### fixed point attractor

#### unstable fixed point



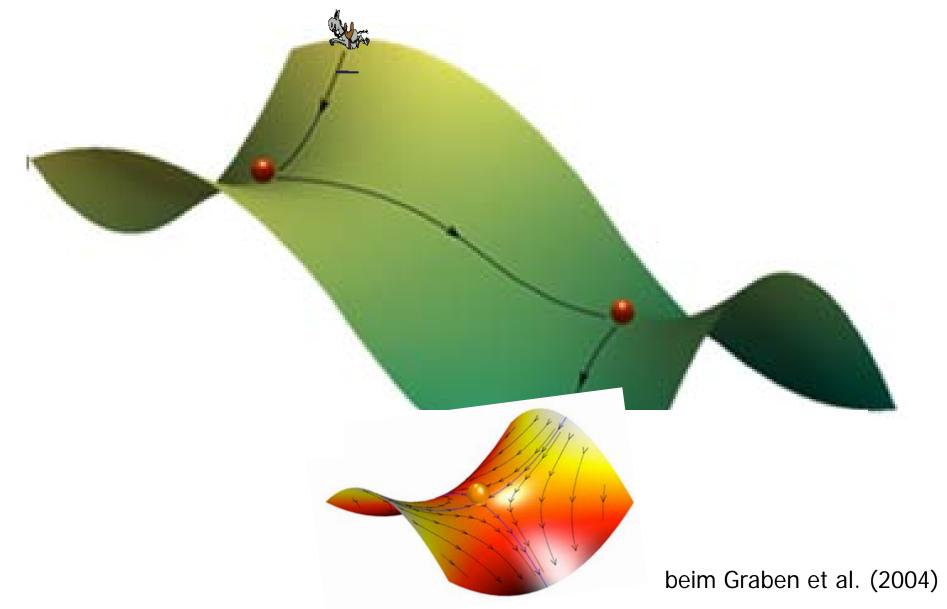
$$|F'(z^*)| < 1$$

$$|F'(z^*)| > 1$$

$$z(t+1) = rz(t)(1-z(t))$$

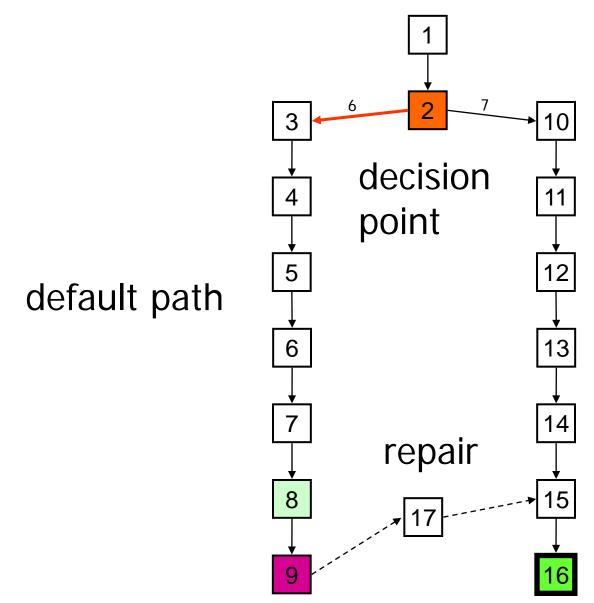






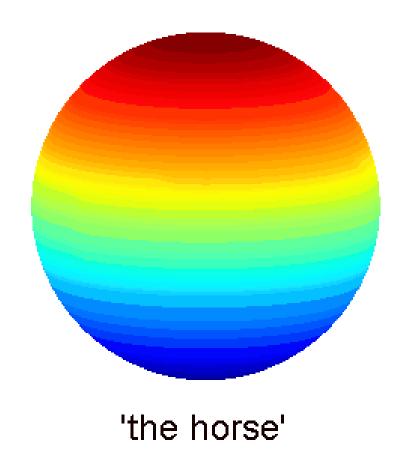












#### Conclusion



- Syntactic parsing represented by sequential dynamics in geometric space
- Intermediate representational states as saddle nodes connected through stable heteroclinic sequences
- Gardenpath states as unwanted attractors
- A\* search as high risk sequential decision strategy
- Syntactic repair as bifurcation of SHS

## Acknowledgements



Thank you for your attention!

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